



Two-Part Reconstruction in Noisy Compressed Sensing

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Motivation

Noisy compressed sensing problem

- Input signal: $x \in \mathbb{R}^N$
- Measurement matrix: $\Phi \in \mathbb{R}^{M \times N}$, often $M < N$
- Measurements: $y = \Phi x + z$, $z \in \mathbb{R}^M$ is noise
- Goal: reconstruct x given Φ and y

Fast CS reconstruction algorithms

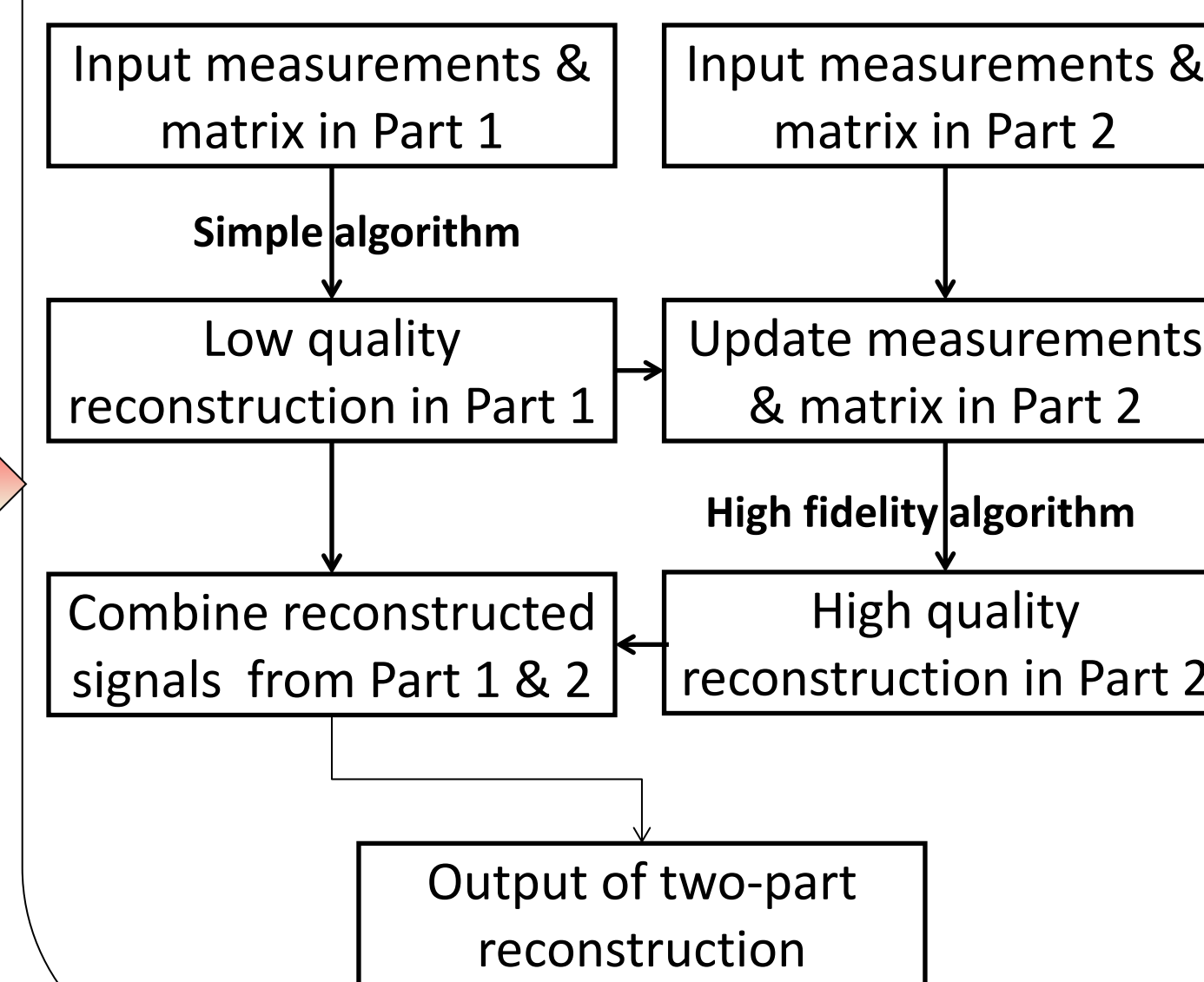
- 😊 Simple and fast
- 😞 Lower fidelity

High fidelity CS reconstruction algorithms

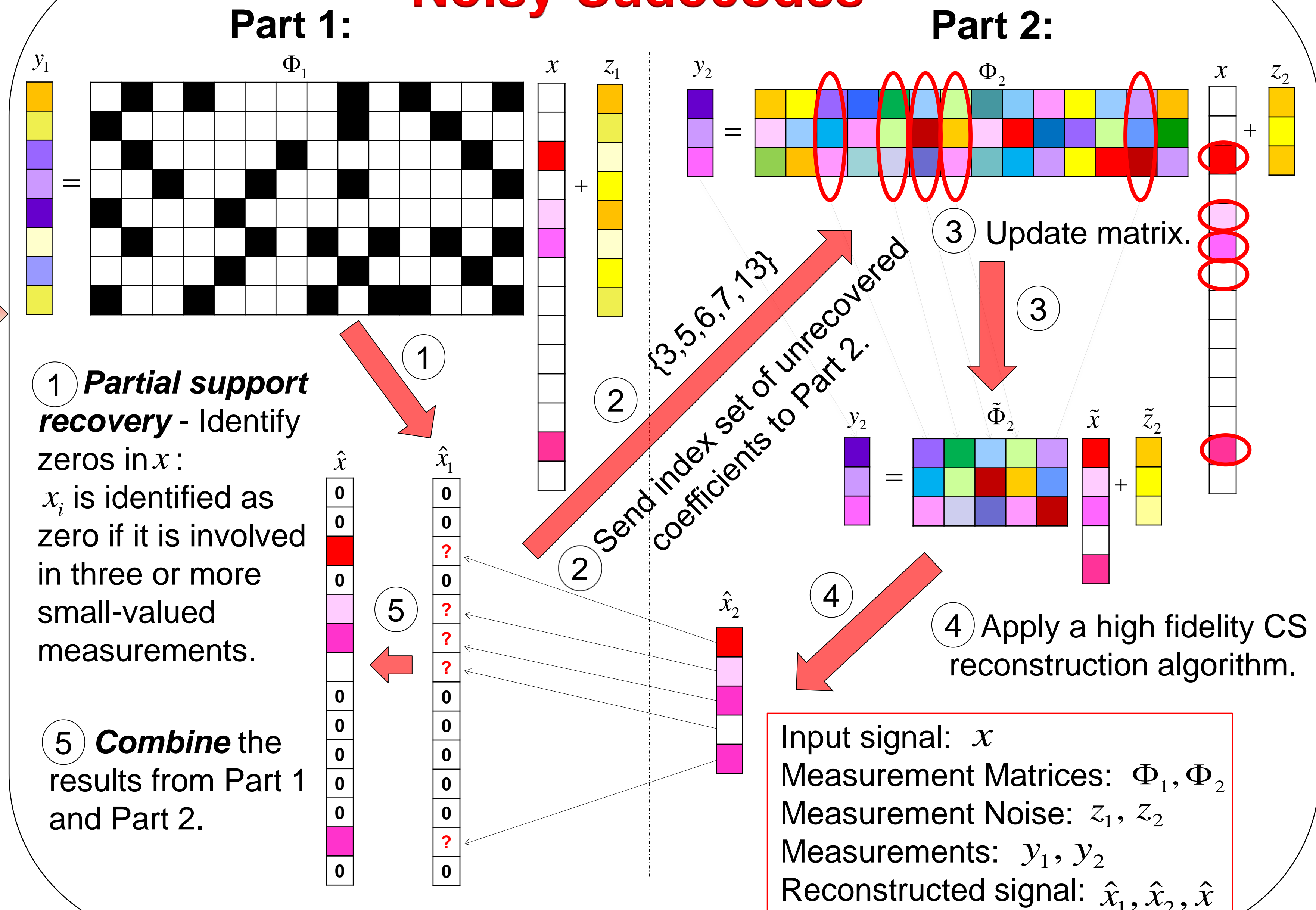
- 😊 Resilient to noise
- 😞 Complex and slow

? What about combining the advantages of different algorithms?

Two-Part Reconstruction



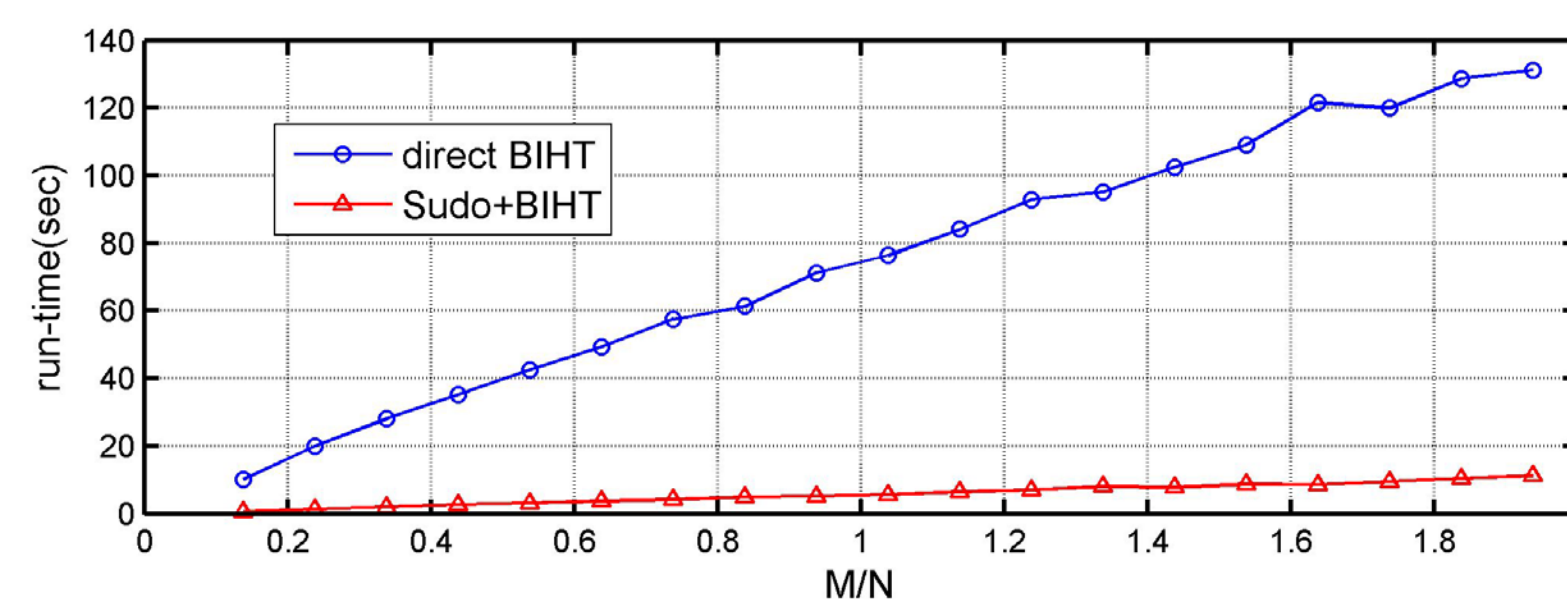
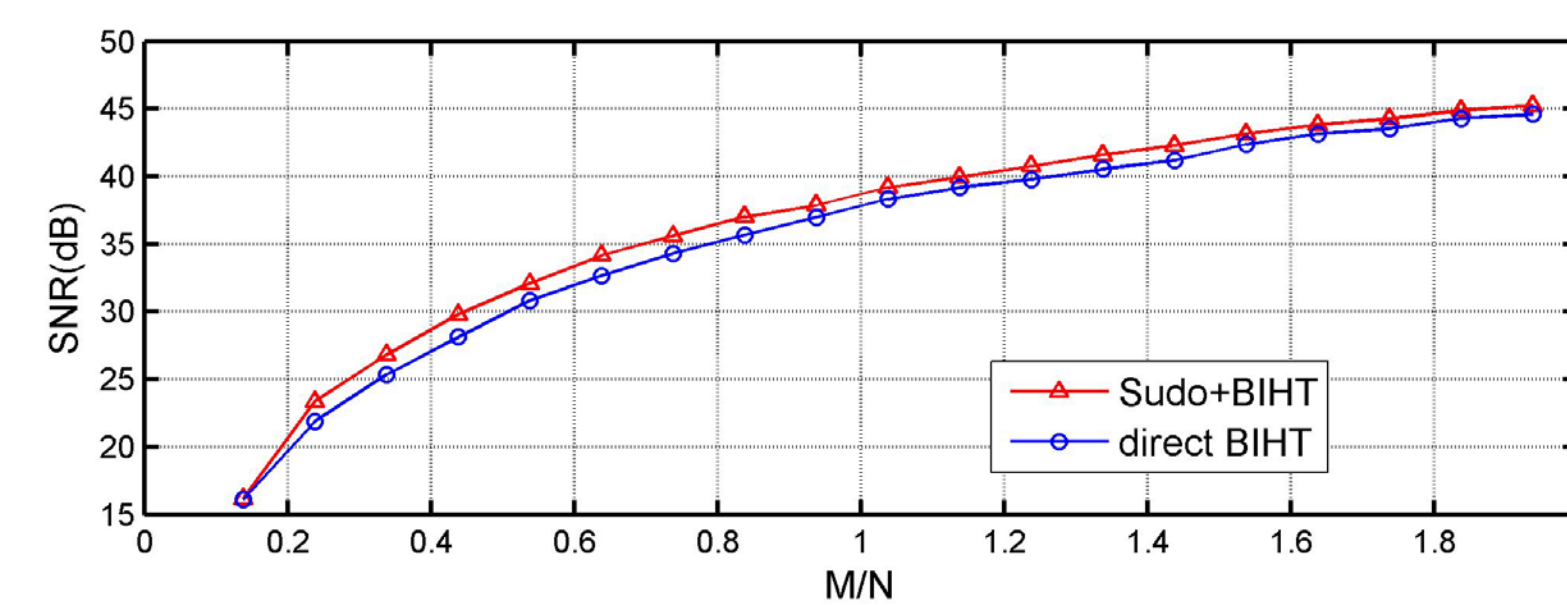
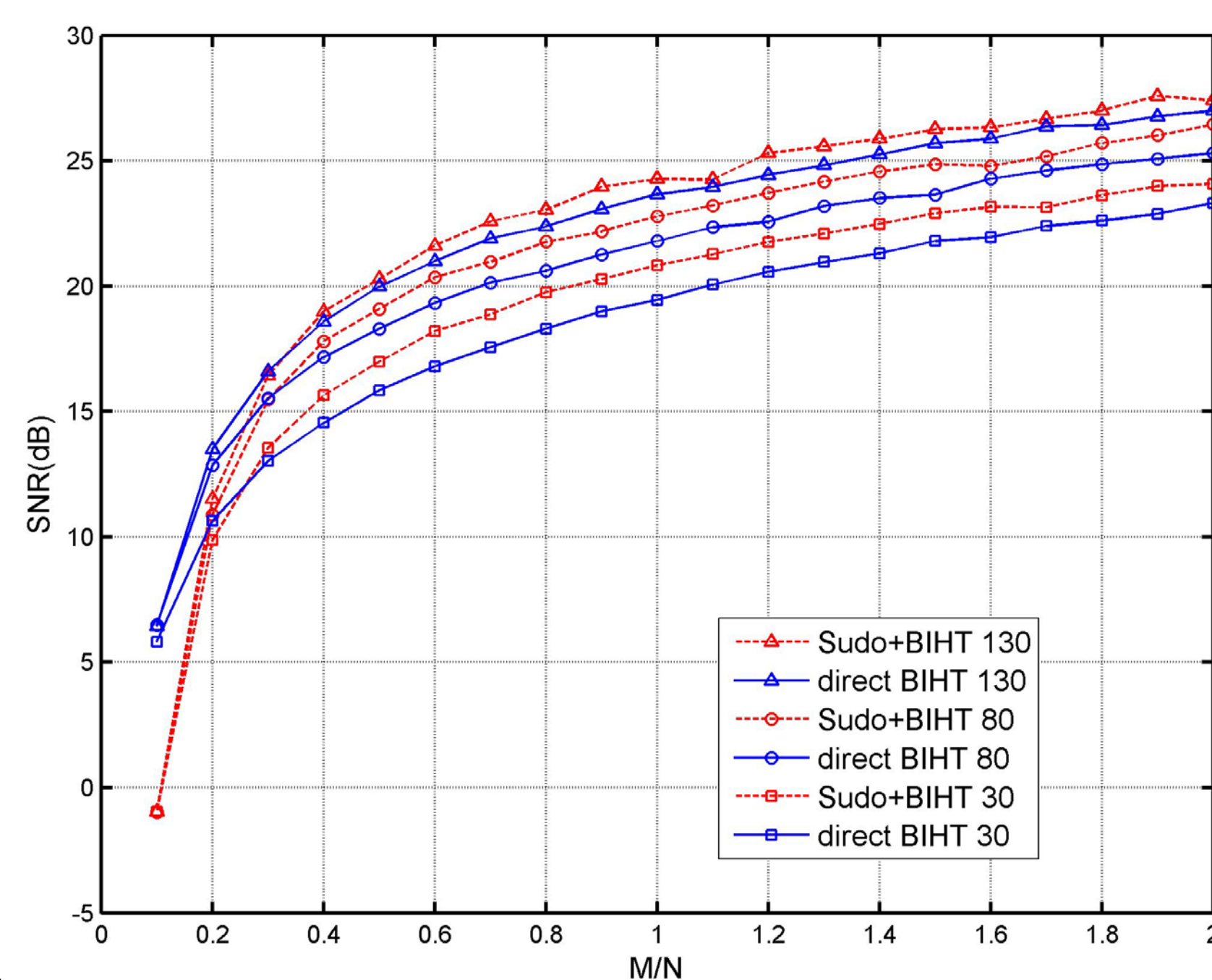
Noisy-Sudocodes



Numerical Results

Experimental setting:

- Compare Sudo+BIHT to original BIHT.
- Sparse Gaussian input x with $\|x\|_2 = 1$; input length $N=10,000$; sparsity $K=50$.
- i.i.d. Gaussian noise $z \sim N(0, \sigma_z^2)$ in noisy setting, where $\sigma_z^2 = 10^{-2.5}$.



Note: Part 1 of Noisy-Sudocodes does not introduce error in noiseless setting.

Conclusion: Noisy-Sudocodes achieve

- Improved SNR
- Reduced run-time

Application to 1-bit CS

➤ Conventional 1-bit quantizer

Noiseless 1-bit CS: $\bar{y} = \text{sign}(\Phi x)$ - quantization noise

Noisy 1-bit CS: $\bar{y} = \text{sign}(\Phi x + z)$ - quantization noise & additive measurement noise

➤ New 1-bit quantizer

$$\bar{y}_j = \begin{cases} 0, & |\langle \Phi_j, x \rangle + z_j| \leq \varepsilon \\ 1, & |\langle \Phi_j, x \rangle + z_j| > \varepsilon \end{cases} \quad \Phi \in \{0,1\}^{M \times N}, j = \{1, \dots, M\}, \Phi_j: \text{the } j\text{th row of } \Phi, \\ \varepsilon \geq 0 \quad (\varepsilon = 0, z = 0 \text{ for noiseless setting}).$$

➤ Noisy-Sudocodes applied to 1-bit CS (Sudo+BIHT)

Part 1: utilize the new 1-bit quantizer;

Part 2: utilize existing 1-bit CS algorithm: Binary Iterative Hard Thresholding (BIHT). BIHT-1 for noiseless setting; BIHT-12 for noisy setting.