

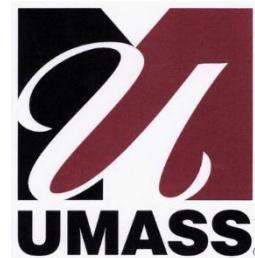
# Universal MAP Estimation in Compressed Sensing



Dror Baron



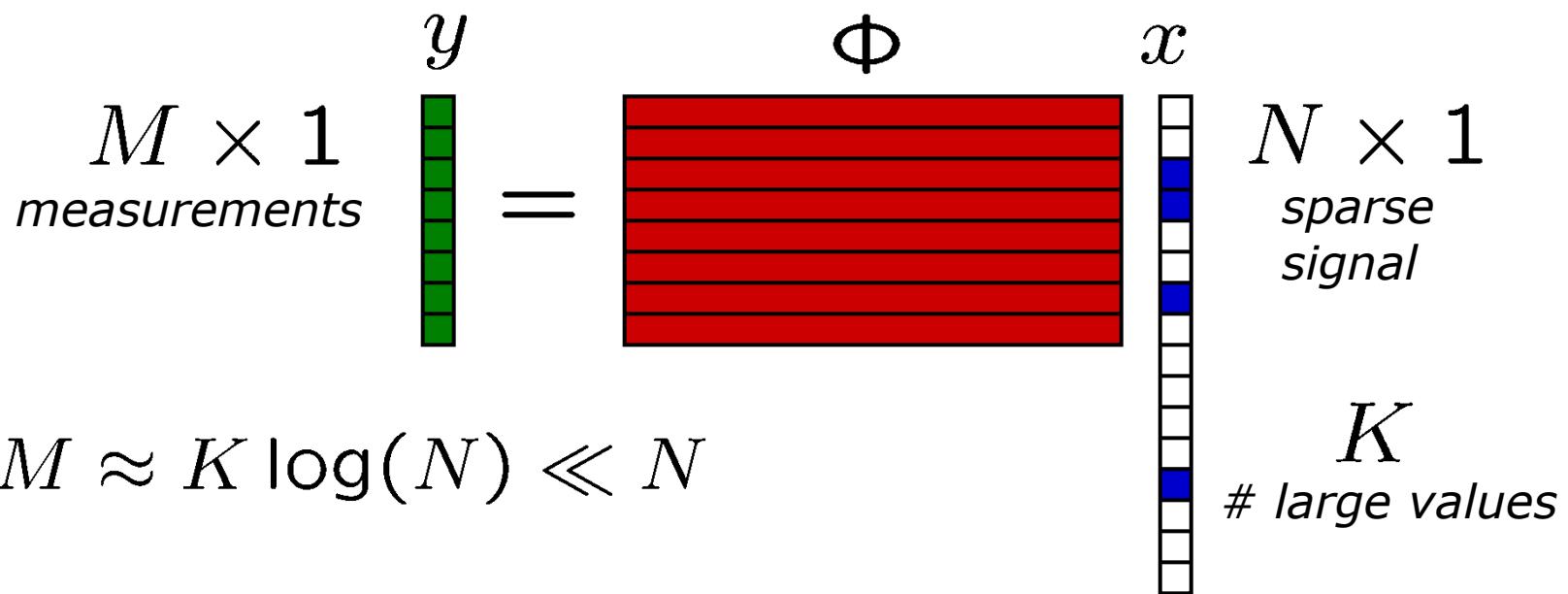
Marco F. Duarte



# Compressed Sensing 101

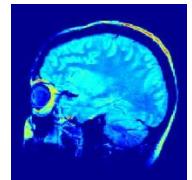
- Length- $N$  input  $x$ , matrix  $\Phi$ ,  $K$  large coefficients
- $M \approx K \log(N) \ll N$  measurements suffice for robust signal reconstruction

$$y = \Phi x + z$$



# Estimation in Linear Mixing

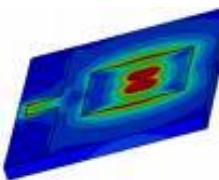
- Medical imaging (tomography)



- Multiuser detection



- Financial prediction



- Electromagnetic scattering



- Seismic imaging (oil industry)

- Compressed sensing



- *Many more...*

*Typically sparse  $x$*

*or compressible  $x$*

*Typically sparse  $x$*

*or compressible  $x$*

***How about a SIMPLE  $x$ ?***

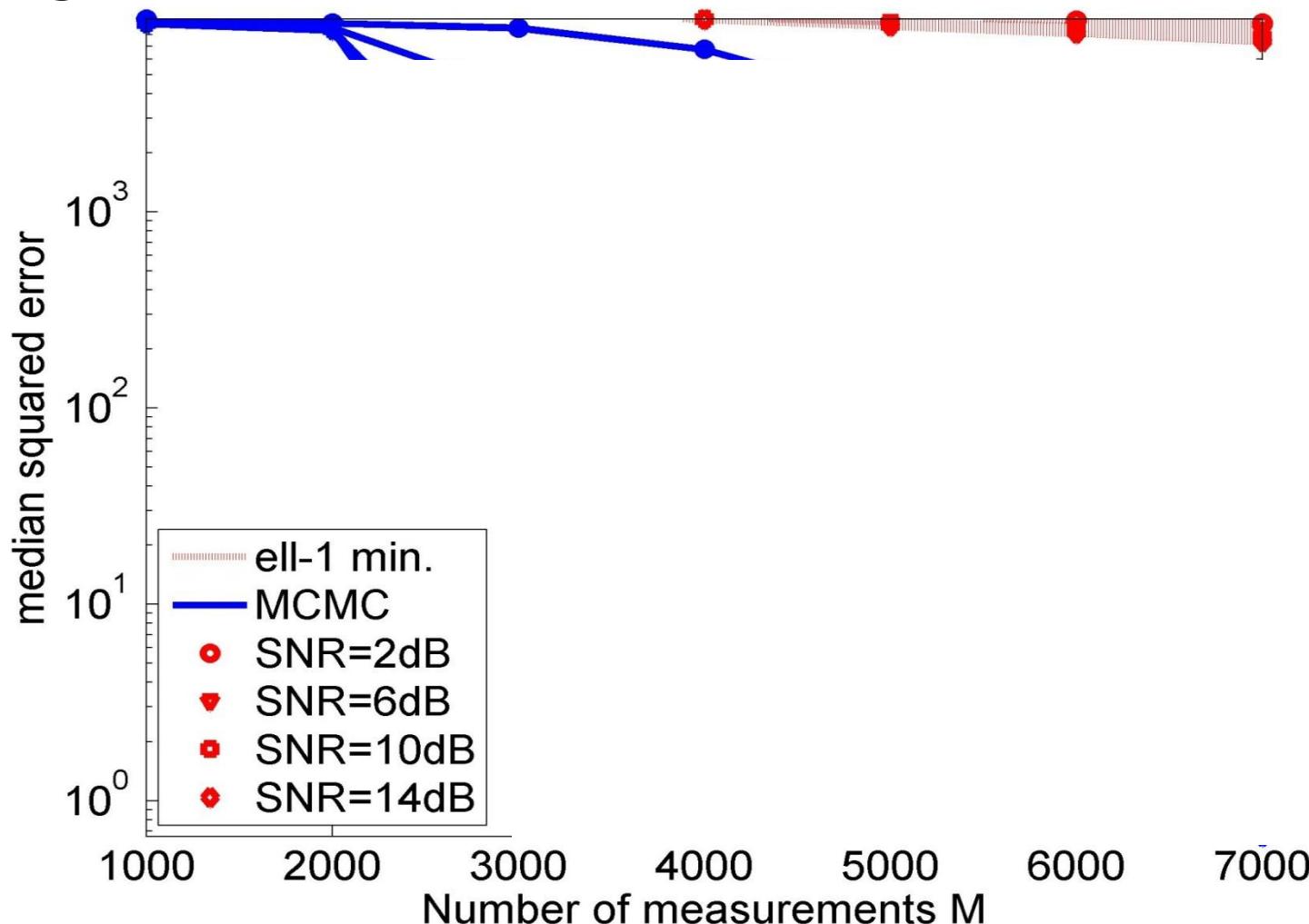
[Donoho et al. 2006]

# Reconstructing *Simple* Source [N=10,000]

- $x$  generated by four state Markov
- 1 1 -1 -1 1 1 -1 -1 1 1 -1 -1...
- 3% glitches in state transitions

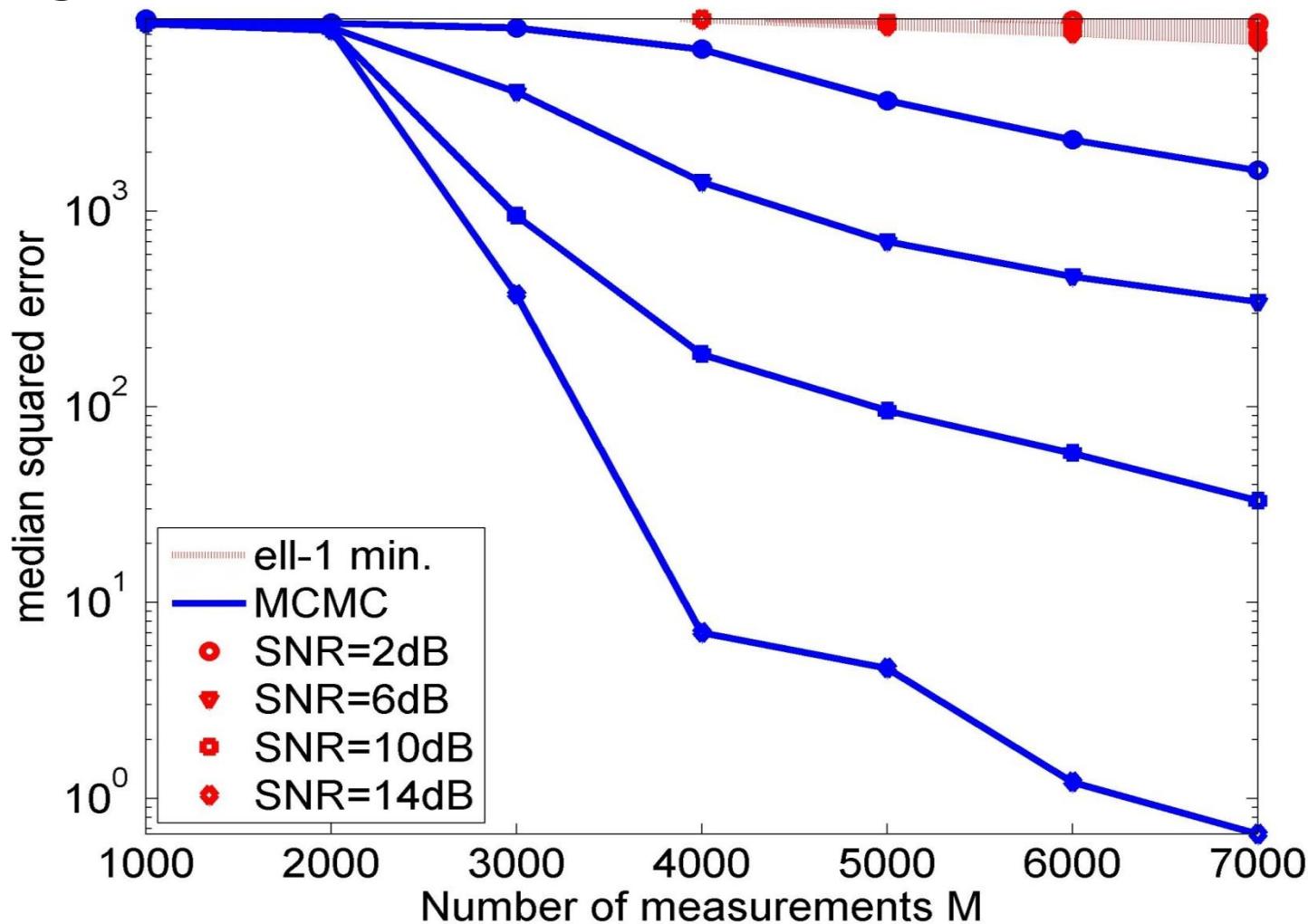
# Reconstructing *Simple* Source [N=10,000]

- $x$  generated by four state Markov
- 1 1 -1 -1 1 1 -1 -1 1 1 -1 -1...
- 3% glitches in state transitions



# Reconstructing *Simple* Source [N=10,000]

- $x$  generated by four state Markov
- 1 1 -1 -1 1 1 -1 -1 1 1 -1 -1...
- 3% glitches in state transitions



***How Did We Do That???***

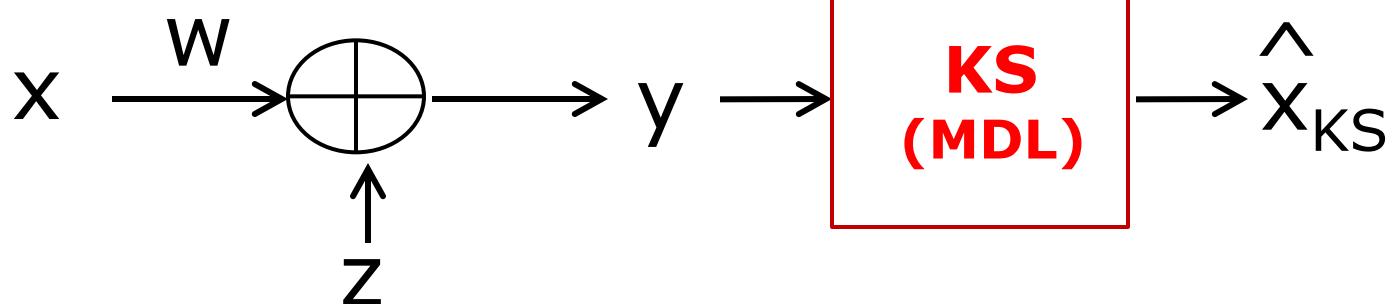


# Kolmogorov Sampler [Donoho 2002]

- AWGN *scalar channel*  $y = x + z$
- Estimate  $x$  by minimizing for
  - *complexity*  $K(x)$  [Kolmogorov, Rissanen,...]
  - regularized via log loss:  $-\log(f_z(Z=y-x))$
- Kolmogorov sampler = minimum description length



$$\hat{x}_{KS} = \operatorname{argmin}_{\hat{x}} \{K(\hat{x}) - \log(f_z(Z=y-\hat{x}))\}$$

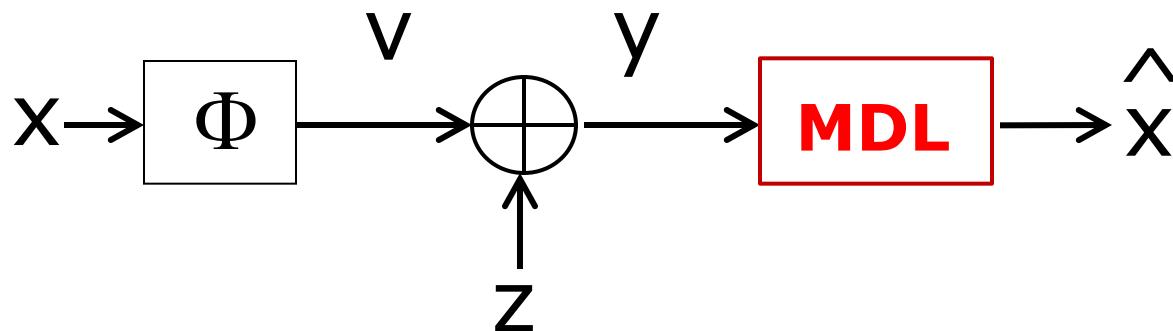


# MDL in CS Estimation

- Estimator *loss/regret*  $-\log(f_{Y|V}(Y=y|V=\Phi x))$
- MDL = maximum *a posteriori* w/ complexity prior

$$\hat{x}_{\text{MDL}} = \operatorname{argmin}_{\hat{x}} \{K(\hat{x}) - \log(f_{Y|V}(Y=y|V=\Phi \hat{x}))\}$$

- Optimization over real-valued  $\hat{x}$  ☹



# Finite Optimization

- **MAIN IDEAS**
  - (1) *Quantize* with reproduction levels  $R$
  - (2) *Encode*  $R(\hat{x})$  with universal coding length  $U(R(\hat{x}))$ 
    - details of  $U$  later
- **Theorem**: regret for discretized grid  $\varepsilon$ -close to regret over continuous space
- Replaced real-valued by finite optimization ☺



# *Is MDL Estimation Good?*

- Scalar channel  $\Phi=I$ ,  $y=x+z$ :  
 $E[(x_{KS}-x)^2]$  is *double* the Bayesian minimum mean square error (MMSE)
- **Conjecture**:  $E[(\hat{X}_{MDL}-x)^2]=2\text{MMSE}$  in  $y=\Phi x+z$  channel
- **Conjecture**:  $\varepsilon$ -weaker performance using quantized grid and universal code  $U(R(\hat{x}))$
- Double the MMSE is ***bad*** for low SNR
- Alternative - *mixture* over all possible  $\hat{x}$  [Baron 2011]



# ***Algorithmic Approach***

Inspired by universal lossy data compression [Weissman et al.]



# Coding Stationary Ergodic Sources

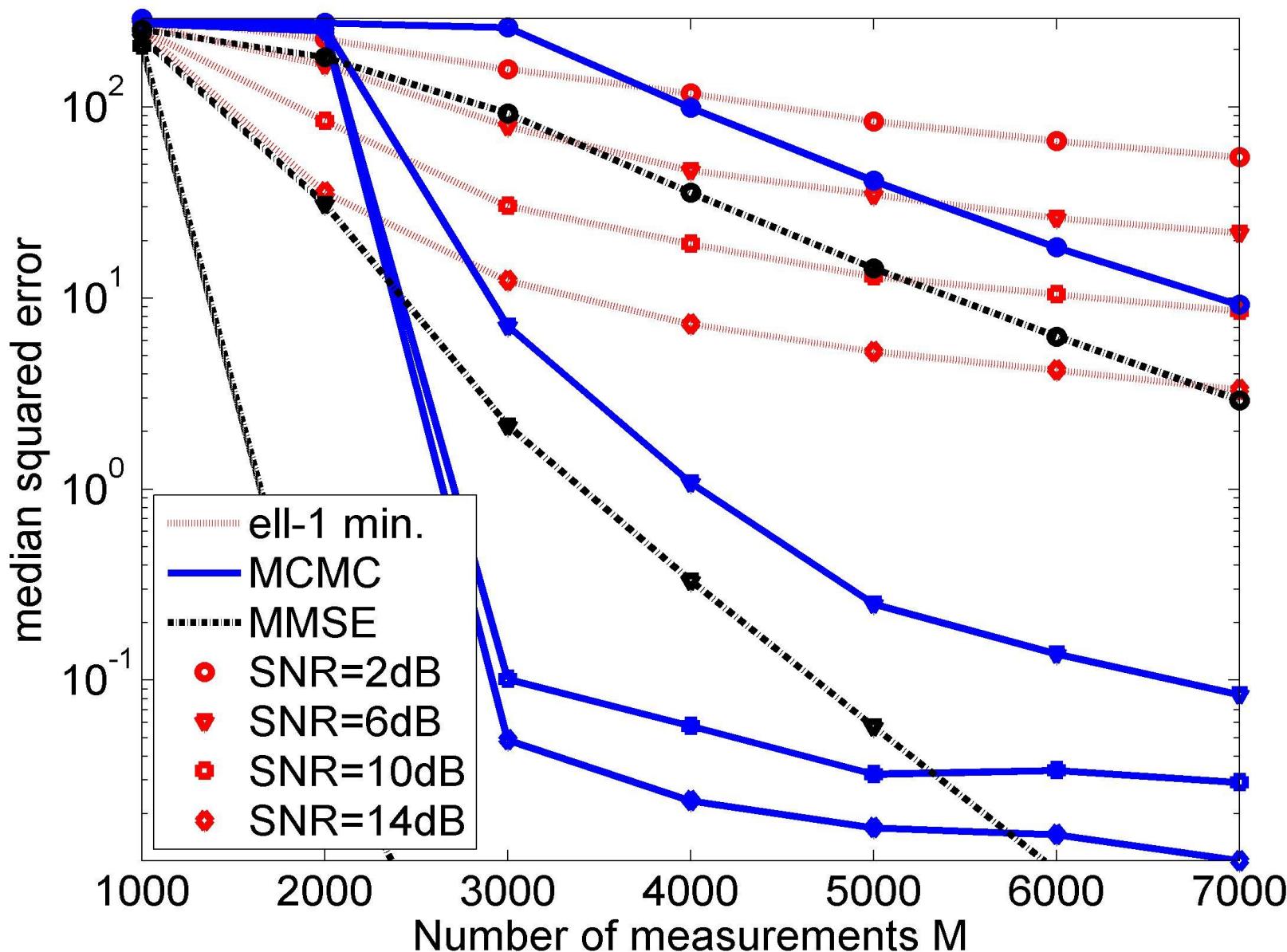
- Assume  $\hat{x}$  generated by stationary ergodic source  $X$ 
  - process  $\hat{x}$  over quantized space
- Our ***practical encoder***  $U(\cdot)$  computes:
  - *empirical symbol counts*  $n_q(\alpha, \beta, \hat{X})$
  - # times  $\beta \in R$  appeared after *context*  $\alpha \in R^q$  in  $\hat{X}$
  - empirical conditional probabilities  $p_q(\beta | \alpha, \hat{X})$
- Empirical conditional *entropy*
$$U(\hat{X}) = H_q(\hat{X}) = -\sum_{\alpha, \beta} n_q(\alpha, \beta, \hat{X}) \log(p_q(\beta | \alpha, \hat{X}))$$
- $H_q(\cdot)$  quantifies likelihood for unknown stationary ergodic  $X$  as  $N \rightarrow \infty$

# Markov Chain Monte Carlo (MCMC)

- Initialize  $\hat{x}$  (over quantized space)
- Process one symbol  $\hat{x}_i$  at a time
- Generate  $\hat{x}_i$  randomly from Gibbs distribution
- Probability based on
$$\Pr(\hat{x}) \propto \exp\{-\mathbf{S} \cdot (\mathbf{U}(\hat{x}) - \log(f_{Y|W}(W=y|W=J(\hat{x}))))\}$$
- Analogous to heat bath concepts in statistical physics
  - inverse temperature  $s$
  - gradual cool-down

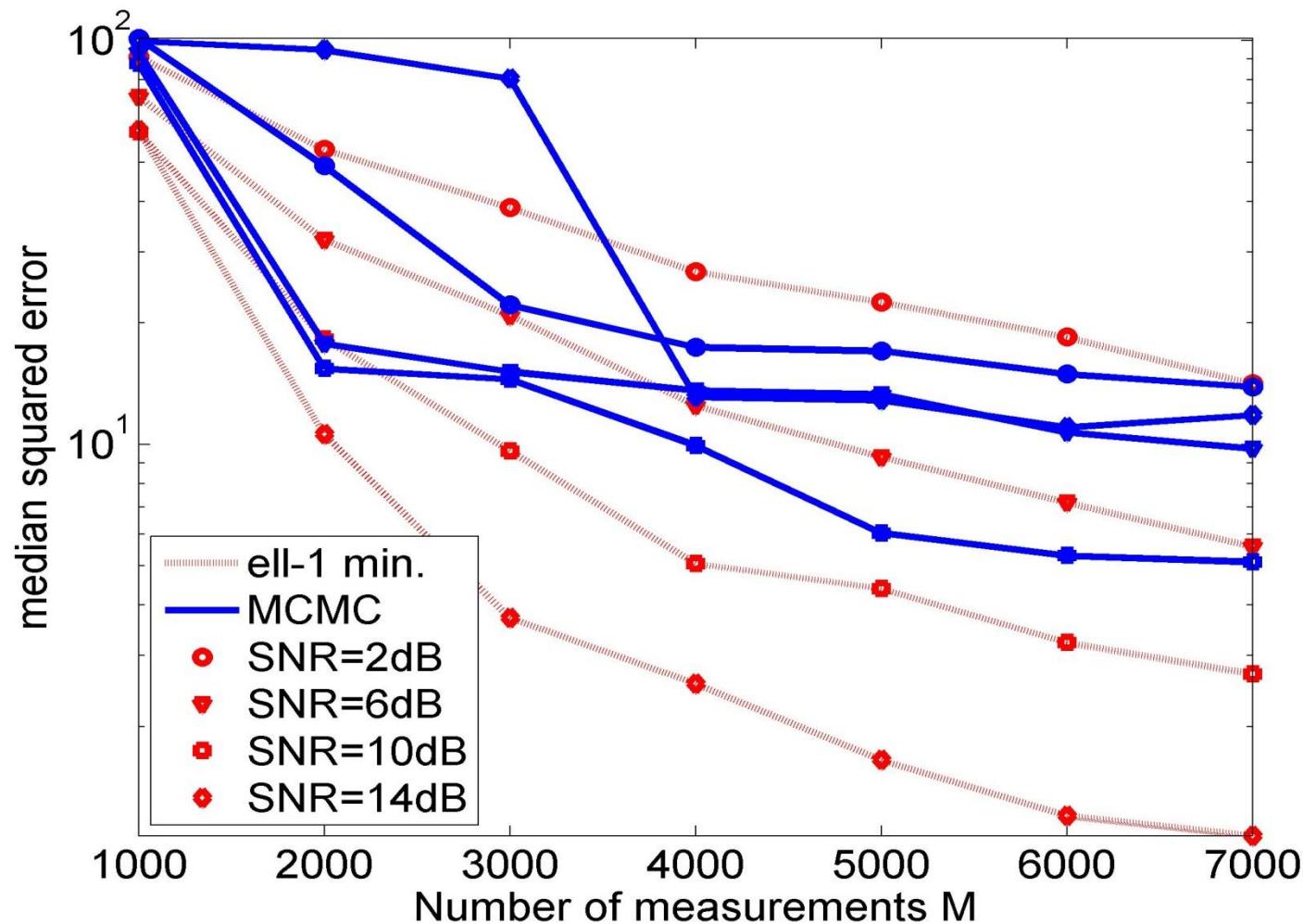


# Performance [x Bernoulli, N=10,000]



# Performance [N=10,000]

- Support set nonzero 3% of time
- Nonzero runs of length  $\sim 10$  times
- Uniform  $U[0,1]$  when nonzero



# Challenges

- Strong dependence on initialization point
- Robust + adaptive reproduction levels R
- More sophisticated algorithms (mixtures?)
- Application-specific families of priors (e.g., images)
- Rigorous theoretical justification for  $\text{MSE}=2\text{MMSE}$
- **Download our software!!**

[people.engr.ncsu.edu/dzbaron/software/UCS\\_BaronDuarte](http://people.engr.ncsu.edu/dzbaron/software/UCS_BaronDuarte)

**THE END**